

NVisage Fusion® Software

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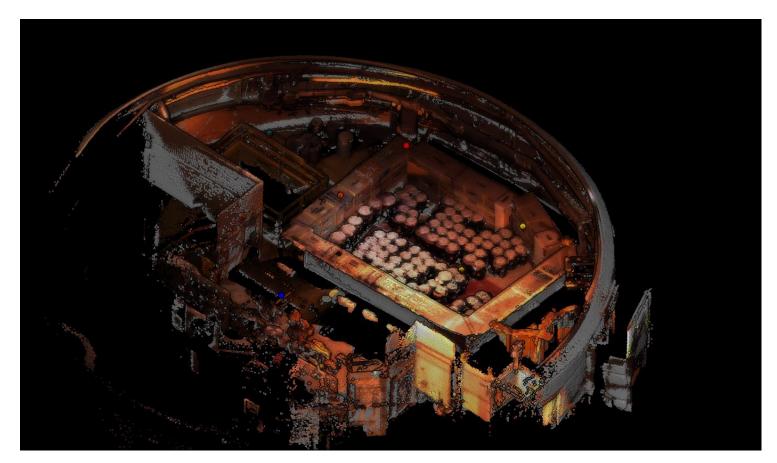
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Create Technologies

- Specialise in applied imaging and sensing R&D
- Founded 2010 as part of the R3i group, from a nuclear consultancy in the UK
- N-Visage™ nuclear characterisation system
- Developing a range of characterisation tools for a wide variety of challenging applications
- Winner Queen's Award for Enterprise 2018 International Trade

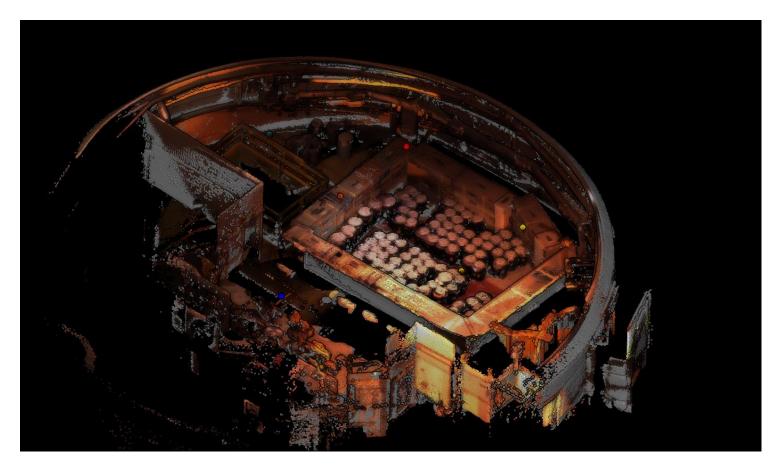




NVisage Fusion topics

- Aims
- Case study
- Algorithms
- Equipment
- Further work
- Conclusion





NVisage Fusion aims

- Combines Radiometric data and 3D geometric data (like CAD, LIDAR scanner)
- Calculates dose uptake for any location
- Calculate activities
- Calculate potential shield effectiveness



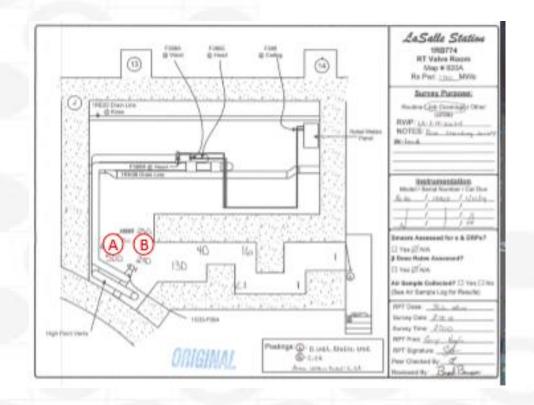
LaSalle case study

- Real world study
- LaSalle GE BWR
- Maintenance of a valve during outage
- NVisage Scanner took data
- 3D point cloud radiation model
- Optimised shield package
- Aim: reduce doserate by 50%





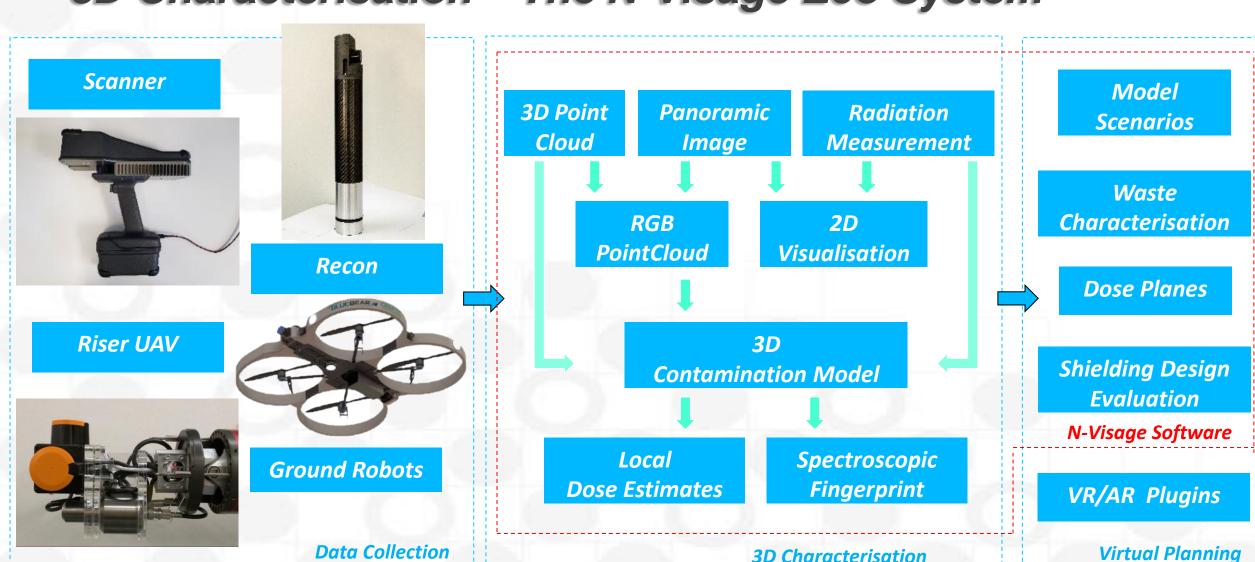
LaSalle – RT Valve room







3D Characterisation – The N-Visage Eco System

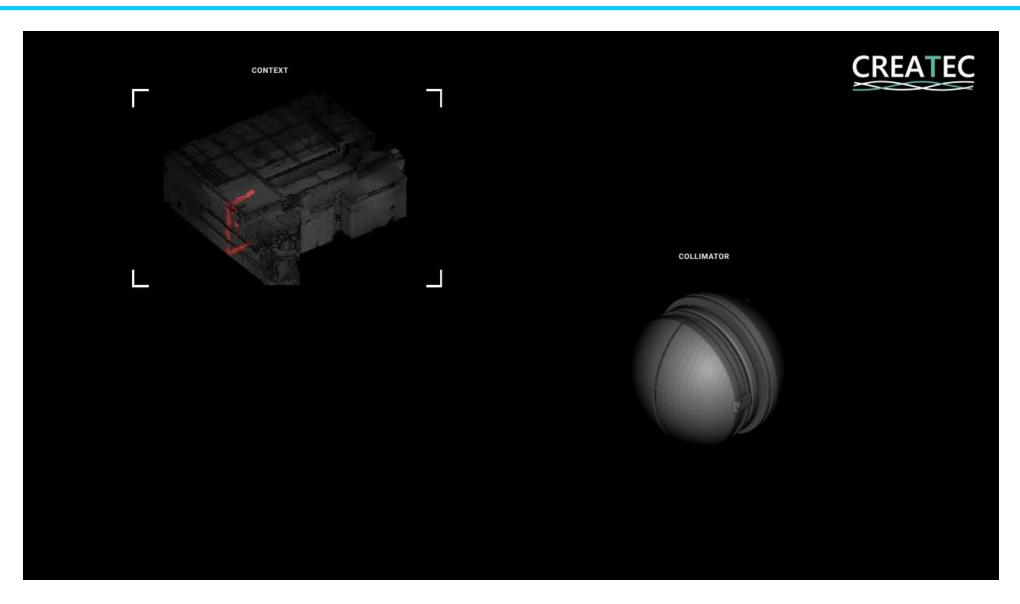




NVisage Fusion data sources

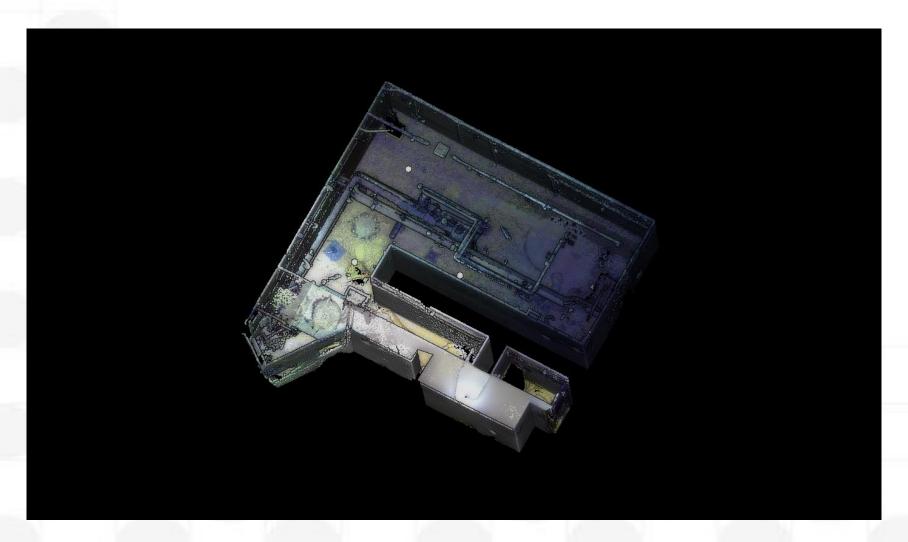
- Createc have products to simultaneously get the location, geometry and radiometric data.
- NVisage Scanner[®] scans the room from a stationary location by moving a collimator around the detector.







Using the scanner





NVisage Fusion method

- Sources (s)
 - points in space (xyz) potential sources of activity
- Readings (<u>d</u>)
 - Location, pose and dose or net peak area
- A is the matrix defining the distance between each *i* and *j* source and reading, the shielding between them and the detector efficiency at that pose.



NVisage Fusion method

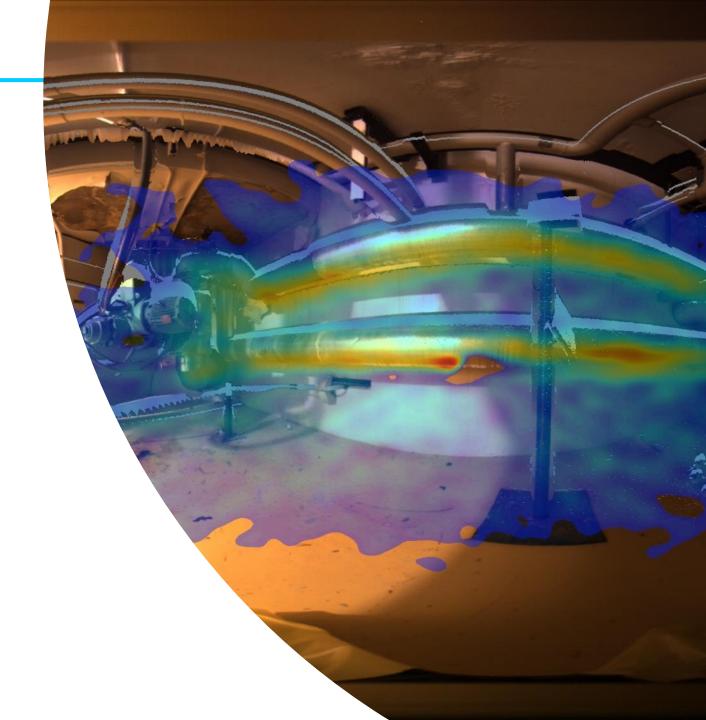
• A is the matrix defining the reduction in intensity with the distance between each *i* and *j* source and reading, the shielding between them and the detector efficiency at that pose.

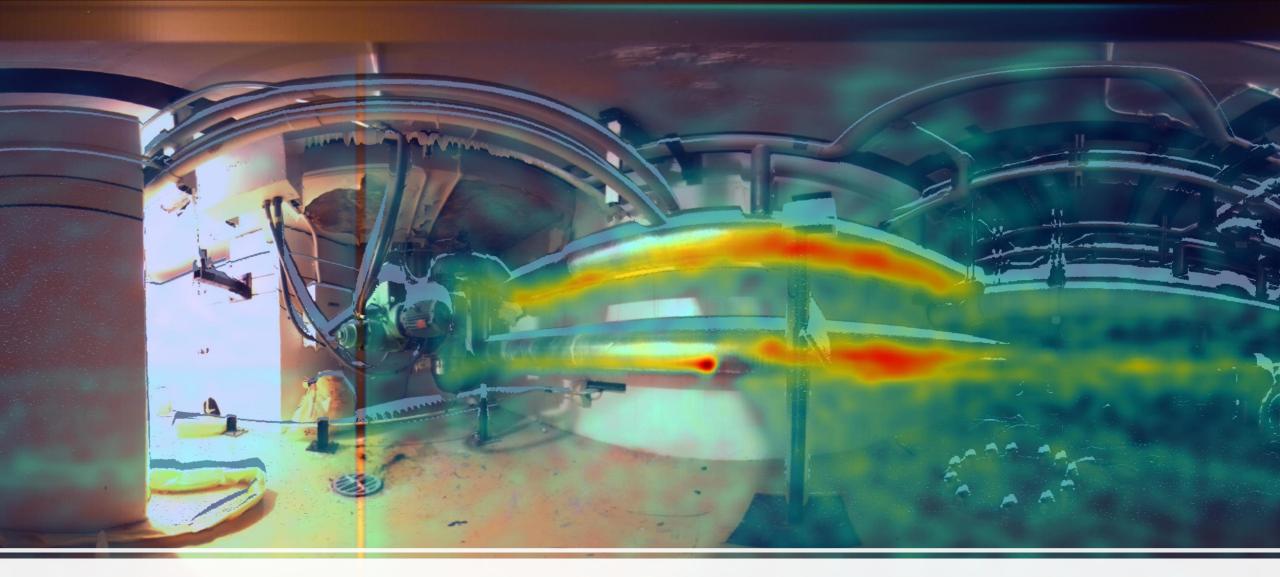
$$A_{ij} = \frac{Ke^{-\lambda_{ij}}}{r_{ij}^2}$$



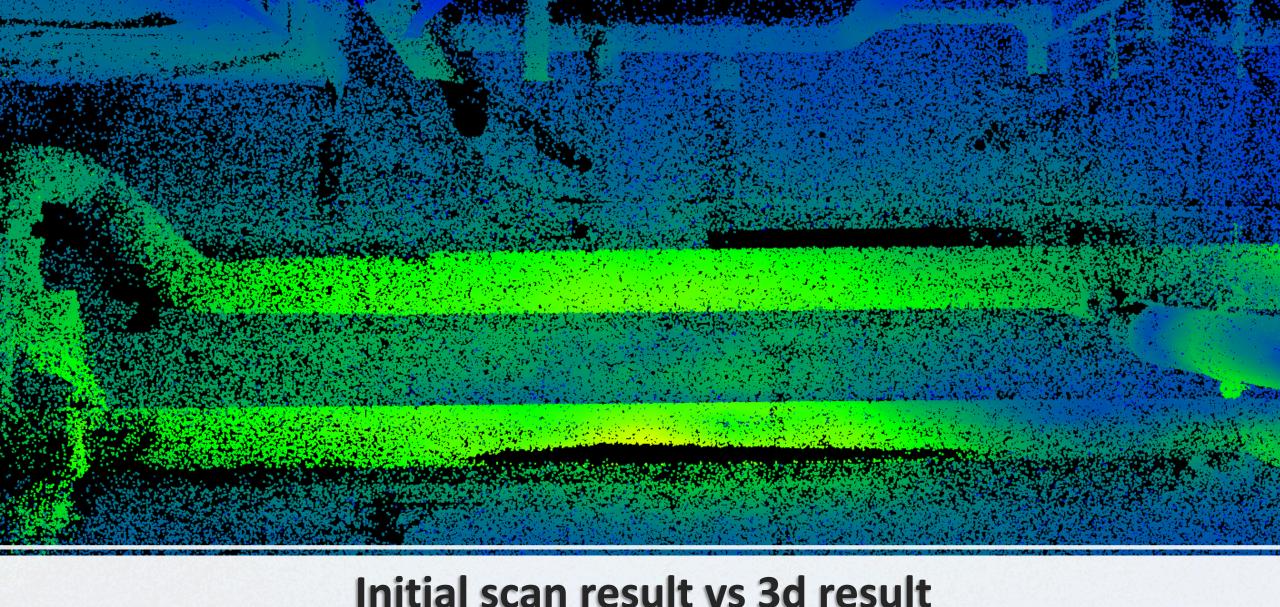
NVisage Fusion method

- Linear equation of underdetermined system
- multiple solutions
- Searching for best solution
- Positive constraint
- Minimise L2-norm.
- ART/ projected Landweber





Initial scan result vs...

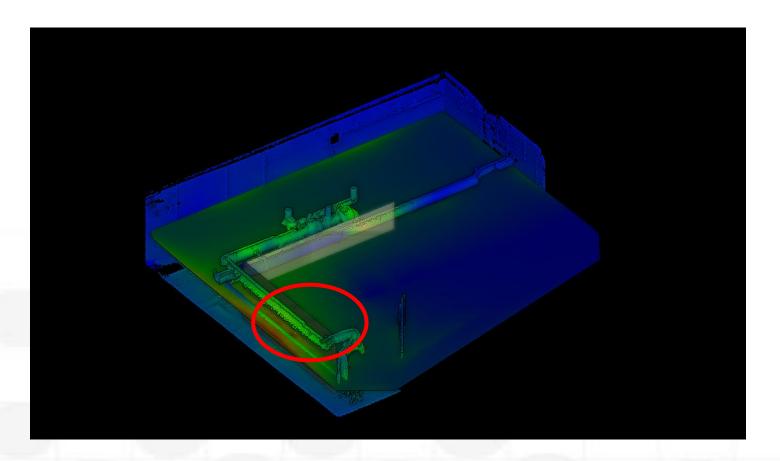


Initial scan result vs 3d result



LaSalle - RT Valve room

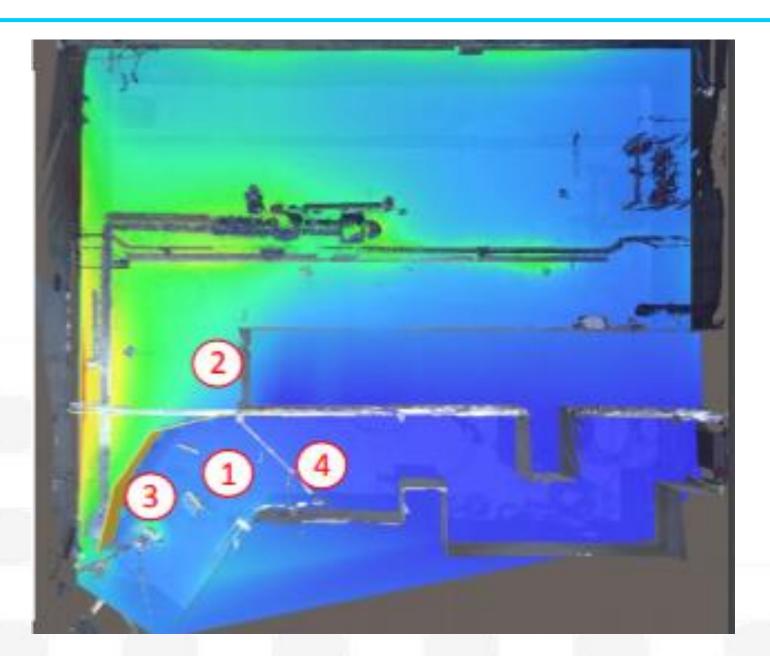
- Solution shows activity on pipes and valve
- Doseplane shows higher rates (circled red) for workers





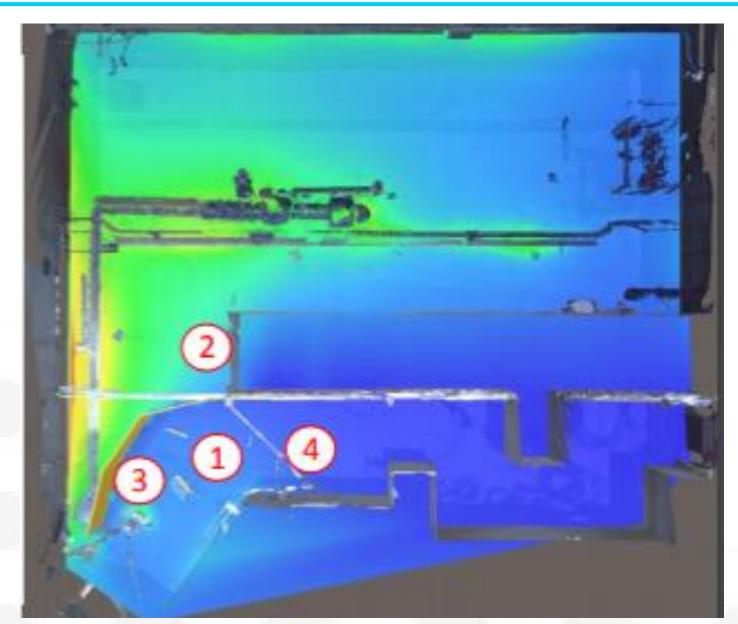
LaSalle - RT Valve room

- Several different shield arrangements were tried to reduce worker dose
- Curved shield optimal



LaSalle - RT Valve room

| Location | Hot Spots | Optimized Shielding | | |
|----------|-----------|---------------------|-------------|--|
| | mRem/h | mRem/h | % Reduction | |
| 1 | 756 | 422 | 45% | |
| 2 | 901 | 824 | 10% | |
| 3 | 1242 | 414 | 68% | |
| 4 | 286 | 169 | 42% | |

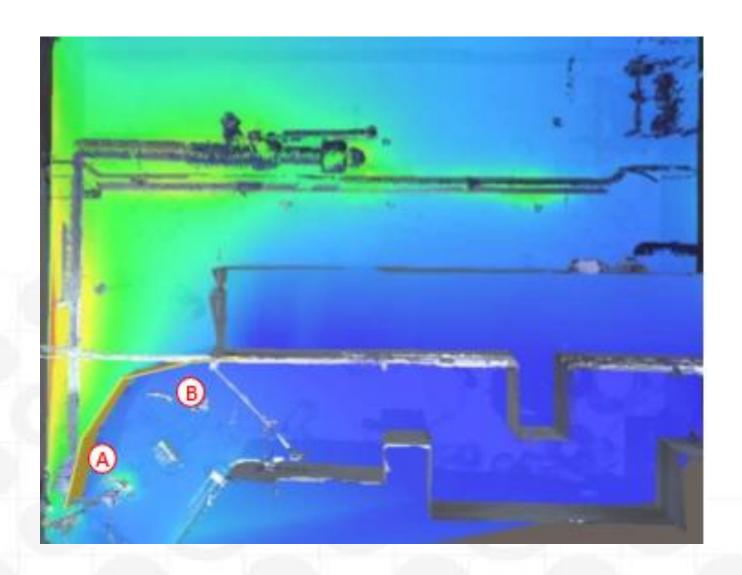




LaSalle shielding solution

- Reduction in doserates with a shield added
- The shield was added and comparison between calculated and survey shows good agreement

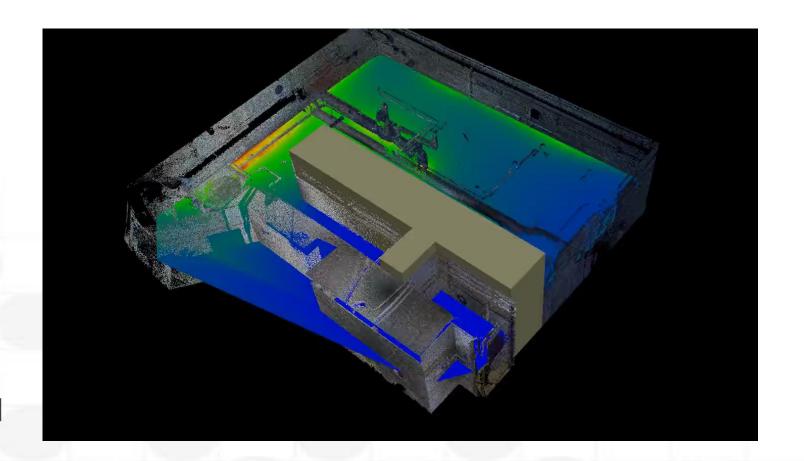
| Survey Location | Survey Data | RadVision³ ^{D®} Data | % Error |
|-----------------|-------------|-------------------------------|---------|
| A | 500 mRem/h | 483 mRem/h | 3.5% |
| В | 290 mRem/h | 270 mRem/h | 7.4% |





Future developments

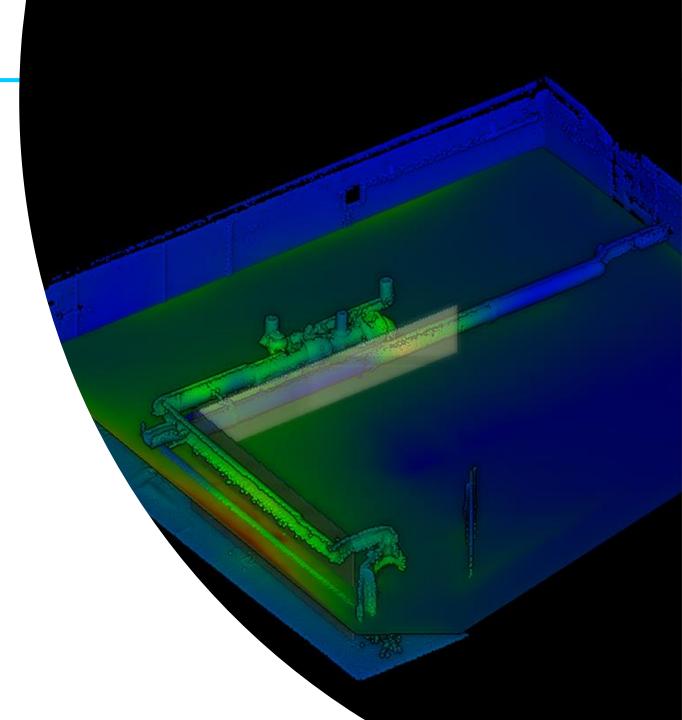
- VR worker training
- Aim to put the worker in the environment
- Give them training on where to work, how long they have
- Perhaps even virtually move shields in or cut items out in real time and see the effect on the doseplanes





Conclusion

- NVisage Fusion can take multiple radiation readings,
- Geometry in CAD or LIDAR measurements
- Shielding structures from CAD
- Analyse to locate the source of radiation
- Solve to calculate dose rate anywhere
- Add shielding in the model to work out the effectiveness.



NVisage RECON®

Cost saving by reducing survey times
Guided route plan shown on display
Minimise human exposure to radiation
Simple intuitive user interface for non-expert users

Accurate record of user route and movements

Plan of survey area produced

Location of contamination can be shown on 2D plan or 3D model



